MRO

Cam Positioner

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments. Refer to Warranty and Application Considerations (page 131), and Safety Precautions (pages 115 and 116)

This Compact Cam Positioner, Popular for It's Ease-of-use, Now Comes with Even **Better Functions.**

- Compact 8-, 16-, and 32-output Models available that are 1/4-DIN size at 96 x 96 mm.
- High-speed operation at 1,600 r/min and high-precision settings to 0.5° ensure widespread application.
- Highly visible display with backlit negative transmissive LCD.
- Advance angle compensation function to compensate for output delays.
- Bank function for multi-product production (8 banks). (H8PS-16 /-32 models.)



Features

Models with 8, 16, or 32 Outputs

The lineup includes Models with 32 outputs in a compact 1/4-DIN size. Using the optional Parallel Input Adapter (Y92C-30) enables expanding to up to 64 outputs for one encoder to support anything from a simple positioning application to a large-scale system.



Simple Programming

The programming method is designed based on a one key-one action concept for settings that could not be simpler. Both initial settings and factory adjustments are effort-free.

Large, Backlit Negative LCDs

Large LCDs, red for the process value and green for set values, show a wealth of operation information, making operating status visible at a glance.

High Speed Up To 1.600 r/min High Precision Up To 0.5° (at 720 Resolution)

High-speed, high-precision applications can be easily handled and productivity increased.

Bank Function for Multi-product Production

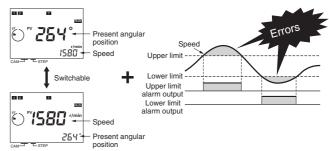
Up to eight different programs can be registered in advance to enable fast and easy switching between products (16/32-output Models only).

USB Communications for Easy Setting from a Computer

Optional Support Software can be used to enable programming from a personal computer via USB communications. Programs can be easily copied, saved, printed, and much more.

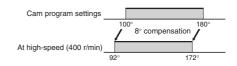
Speed Display and Speed Alarm Output

Both the speed (rotations/minutes) and present angular position can be displayed at the same time. Alarm outputs can be produced for both upper and lower speed limits.



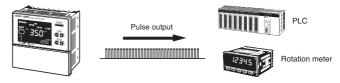
Advance Angle Compensation Function to **Compensate for Output Delays**

The advance angle compensation (ADV) function automatically advances the ON/OFF angle of outputs in proportion to machine (encoder) speed to compensate for the delay in timing of ON/OFF operation. ADV values can be set individually for 7 cam outputs.



Pulse Output for Timing Control

The number of pulses per rotation and the pulse output start angle can be set to enable operations like adjusting timing with a PLC or outputting to a rotation meter.



Model Number Structure

Model Number Legend

H8PS-1 2 3 4 1. Number of outputs

8: 8 outputs 16: 16 outputs 32: 32 outputs 2. Panel language B: English

Ordering Information

■ List of Models

Cam Positioner

Number of outputs	Mounting method	Output configuration	Bank function	Model
8 outputs	Flush mounting	NPN transistor output	No	H8PS-8B
		PNP transistor output		H8PS-8BP
	Surface mounting/	NPN transistor output		H8PS-8BF
	track mounting	PNP transistor output		H8PS-8BFP
16 outputs	Flush mounting	NPN transistor output	Yes	H8PS-16B
		PNP transistor output	-	H8PS-16BP
	Surface mounting/ track mounting	NPN transistor output		H8PS-16BF
		PNP transistor output		H8PS-16BFP
32 outputs	Flush mounting	NPN transistor output		H8PS-32B
		PNP transistor output		H8PS-32BP
	Surface mounting/	NPN transistor output		H8PS-32BF
	track mounting	PNP transistor output		H8PS-32BFP

Dedicated Absolute Encoder

Туре	Resolution	Cable length	Model
Economy	256	2 m	E6CP-AG5C-C 256 2M
Standard	256	1 m	E6C3-AG5C-C 256 1M
		2 m	E6C3-AG5C-C 256 2M
	360		E6C3-AG5C-C 360 2M
	720		E6C3-AG5C-C 720 2M
Rigid	256	2 m	E6F-AG5C-C 256 2M
	360		E6F-AG5C-C 360 2M
	720		E6F-AG5C-C 720 2M

Accessories (Order Separately)

Name	Specification	Model	
Discrete Wire Output Cable	2 m	Y92S-41-200	
Connector-type Output Cable	2 m	E5ZE-CBL200	
Support Software	CD-ROM	H8PS-SOFT-V1	
USB Cable	A miniB, 2 m	Y92S-40	
Shaft Coupling for the E6CP	Axis: 6 mm dia.	E69-C06B	
Shaft Coupling for the E6C3	Axis: 8 mm dia.	E69-C08B	
Shaft Coupling for the E6F	Axis: 10 mm dia.	E69-C10B	
Extension Cable (See note.)	5 m (same for E6CP, E6C3, and E6F)	E69-DF5	
Parallel Input Adapter	Two Units can operate in parallel.	Y92C-30	
Protective Cover		Y92A-96B	
Watertight Cover		Y92A-96N	
Track Mounting Base		Y92F-91	
Mounting Track	50 cm × 7.3 mm (ℓ × t)	PFP-50N	
	1 m × 7.3 mm (ℓ × t)	PFP-100N	
	1 m × 16 mm (ℓ × t)	PFP-100N2	
End Plate		PFP-M	
Spacer		PFP-S	

Note: Ask your OMRON representative about the availability of non-standard lengths.

- F: Surface mounting/ track mounting/
- 4. Output configuration None:NPN transistor output P: PNP transistor output

Specifications

■ Ratings

	Item		H8PS-□B	H8PS-□BF	H8PS-□BP	H8PS- BFP			
Rated su	pply volta	ige	24 VDC						
Operatin	g voltage	range	85% to 110% of rated sup	ply voltage					
Mounting	g method		Flush mounting	Surface mounting, track mounting	Flush mounting	Surface mounting, track mounting			
Power co	onsumptio	on	Approx. 4.5 W at 26.4 VD0 Approx. 6.0 W at 26.4 VD0	C for 8-output models C for 16-/32-output models					
Inputs	Encoder	input	Connections to a dedicate	d absolute encoder					
	External inputs	Input signals	8-output Models: None 16-/32-output Models: Bar	nk inputs 1/2/4, origin input,	start input				
		Input type	No voltage inputs: ON imp ON resi Minimu	0 Ω) Applied voltage: 30 VDC max.					
Outputs	Outputs RUN output		NPN open-collector transistor outputsPNP open-collector transistor outputs30 VDC max.,30 VDC max. (26.4 VDC for 16-/32-ou100 mA max. (Do not exceed 1.6 A total for all cam100 mA max. (Do not exceed 1.6 A total for all camoutputs and the RUN output.),outputs and the RUN output.),residual voltage: 2 VDC max.residual voltage: 2 VDC max.		for 16-/32-output Models), eed 1.6 A total for all cam put.),				
	Pulse output		NPN open-collector transis 30 VDC max., 30 mA max., residual voltage: 0.5 VDC	·	PNP open-collector transistor output 30 VDC max. (26.4 VDC for 16-/32-output Models) 30 mA max., residual voltage: 2 VDC max.				
Number of outputs			8-output Models: 8 cam outputs, 1 RUN output, 1 pulse output 16-output Models: 16 cam outputs, 1 RUN output, 1 pulse output 32-output Models: 32 cam outputs, 1 RUN output, 1 pulse output						
Number	of banks		8 banks (for 16-/32-output Models only)						
Display r	nethod		7-segment, negative transmissive LCD (Main Display: 11 mm (red), Sub-display: 5.5 mm (green))						
Memory	backup m	ethod	EEPROM (overwrites: 100000 times min.) that can store data for 10 years min.						
Ambient operating temperature		I	-10 to 55°C (with no icing or condensation)						
Storage	temperatu	ire	-25 to 65°C (with no icing or condensation)						
Ambient	humidity		25% to 85%						
Degree o	of protecti	on	Panel surface: IP40, Rear	case: IP20					
Case col	or		Light gray (Munsell 5Y7/1)						

■ Characteristics

Setting unit 0.5° increments at a resolution of 720, 1° increments at a resolution of 256 or 360 (See note 1.)			720, 1° increments at a resolution of 256 or 360 (See note 1.)			
Number of st	eps	Up to 10 steps can be set for eac	h cam to turn the output ON/OFF 10 times. (See note 2.)			
Inputs	Encoder input	Connections to a dedicated absolute encoder • Response rotation speed (in Run/Test Mode) 1600 r/min max. at a resolution of 256 or 360 (1200 r/min max. if ADV function is set for 4 or more cams) (See notes 3 and 4.) 800 r/min max. at a resolution of 720 (600 r/min max. if ADV function is set for 4 or more cams) • Includes error data detection				
Encoder cable extension distance		 256/360 resolution 100 m max. at 330 r/min or less 52 m max. at 331 to 1200 r/min (331 to 900 r/min if ADV function is set for 4 or more cams) 12 m max. at 1201 to 1600 r/min (901 to 1200 r/min if ADV function is set for 4 or more cams) 720 resolution 100 m max. at 330 r/min or less 52 m max. at 331 to 600 r/min (331 to 450 r/min if ADV function is set for 4 or more cams) 12 m max. at 601 to 800 r/min (451 to 600 r/min if ADV function is set for 4 or more cams) 				
Output respo	onse time	0.3 ms max.				
Insulation re	sistance	100 M Ω min. (at 500 VDC) betwee parts, between all current-carrying	en current-carrying terminals and exposed non-current-carrying metal g parts and the USB connector			
Dielectric str	ength	1000 VAC, 50/60 Hz for 1 min between current-carrying terminals and exposed non-current-carrying metal parts 500 VAC, 50/60 Hz for 1 min between current-carrying section and USB connector, and between current-carrying terminals and non-current-carrying metal part of output connector				
Impulse with	stand voltage	1 kV between power terminals 1.5 kV between current-carrying t	erminals and exposed non-current-carrying metal parts			
		± 480 V between power terminals, ± 600 V between input terminals Square-wave noise by noise simulator (pulse width: 100 ns/1 $\mu s,$ 1-ns rise)				
Static immun	nity	8 kV (malfunction), 15 kV (destruction)				
Vibration	Destruction	10 to 55 Hz with 0.75-mm single amplitude each in 3 directions for 2 hours each				
resistance	Malfunction	10 to 55 Hz with 0.5-mm single amplitude each in 3 directions for 10 minutes each				
Shock	Destruction	300 m/s ² 3 times each in 6 directi	ons			
resistance	Malfunction	200 m/s ² 3 times each in 6 directi	ons			
Approved sa	fety standards	cULus (Listing): UL508/CSA C22	2 No. 14			
EMC		Immunity Burst: Immunity Surge:	EN61326 EN55011 Group1 Class A EN61326 EN61000-4-2: 4 kV contact discharge 8 kV air discharge EN61000-4-3: 10 V/m (Amplitude-modulated, 80 MHz to 1 GHz) 10 V/m (Pulse-modulated, 900 MHz ±5 MHz) EN61000-4-6: 10 V (0.15 to 80 MHz) EN61000-4-4: 2 kV for power-line 1 kV for I/O signal-line EN61000-4-5: 1 kV line to line (power line) 2 kV line to ground (power line)			
Weight		Approx. 300 g (Cam Positioner m	ain unit only)			

Note: 1. Cam output precision, however, is 2° max. for Encoder with 256 resolution (P/R).

2. Although 32-output Models can have 10 steps set for any one output, there must be no more than 160 steps total set for all cam outputs.

3. The maximum is 1000 r/min when an E6CP-AG5C-C Encoder is connected.

4. ADV stands for Advance Angle Compensation.

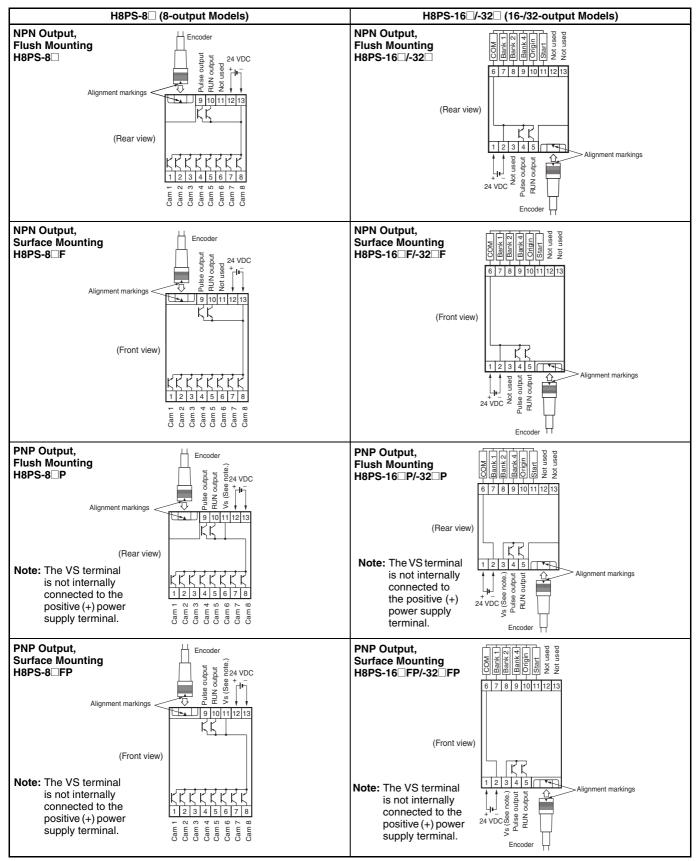
Counters

■ Functions

Item	H8PS-8	H8PS-16□	H8PS-32		
Encoder rotation direction switching	Encoder data can be set with a DI	P switch to forward (CW) or reverse (C0	CW) direction.		
Encoder origin designation	The present display angular position can be set to 0° (origin) by	The present display angular position c origin input terminal or the ORIGIN Ke			
	pressing the ORIGIN Key on the front panel.	Note: All banks use the same origin.			
Angle display switch	Converts the Absolute Encoder va	lue display from 256 divisions/revolutio	n to 360°/revolution.		
Rotation display monitor	Graphically displays the Encoder r	otational angular position.			
Teaching function	Sets the cam output ON/OFF angl	e based on actual machine (Encoder) o	operation.		
Pulse output	Outputs a preset number of pulses	s per Encoder rotation. It also sets the p	oulse output start angle.		
Switching the angle and speed displays	Displays both the present angular position and the number of Encoder revolutions (speed) in Run Mode. Switches back and forth between the main display showing the present angular position with the sub-display showing the speed and the main display showing the speed with the sub-display showing the present angular position.				
Bank function		Enables the entire cam program to be changed at one time by banks (0 to 7). The bank that is running can be switched using the bank input to BANK Key on the front panel. Also enables programs to be copied between banks.			
Advance angle compensation (ADV) function		FF angle of cam outputs in proportion to of ON/OFF operation. ADV values can			
Speed alarm output		ed as an Encoder speed alarm output.			
	The function can output upper and	-			
All protection function	, ,	ions in Run Mode to prevent incorrect o	1		
Cam protection function	1 0 0	cam output level. Any cam numbers can	1		
Step number limit	program.	n be set per cam output. Prohibits inco	rrect operations by adding to the		
Output prohibit		The start input can be turned OFF in F output.	Run or Test Mode to prohibit cam		
		Note: Use this function carefully for the are provided when the start input			
Support Software settings		Programs can be uploaded or downloa computer to the Cam Positioner using separately) and the Support Software	a USB Cable (Y92S-40, sold		

Connections

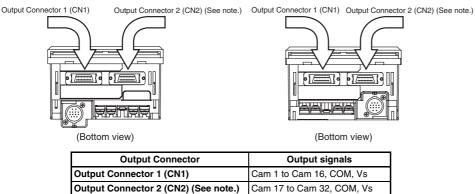
Terminal Arrangement



Output Cable Connections (16-/32-output Models Only)

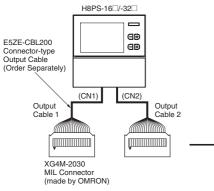
Flush Mounting Models

Surface Mounting Models



Note: The 16-output Models do not have CN2 Connectors.

1. E5ZE-CBL200 Connector-type Output Cable (Order Separately) Connections



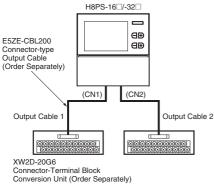
Pin Arrangement of XG4M-2030 Connectors

r.										
	1	3	5	7	9	11	13	15	17	19
	2	4	6	8	10	12	14	16	18	20

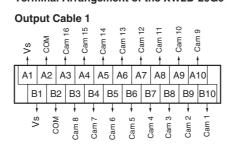
Output Cable 1 Wiring Table

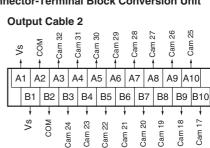
Outputs	Connector pin No.	Outputs	Connector pin No.
Cam 1	20	Cam 9	19
Cam 2	18	Cam 10	17
Cam 3	16	Cam 11	15
Cam 4	14	Cam 12	13
Cam 5	12	Cam 13	11
Cam 6	10	Cam 14	9
Cam 7	8	Cam 15	7
Cam 8	6	Cam 16	5
СОМ	4	СОМ	3
Vs	2	Vs	1

Using Connector-Terminal Block Conversion Units



Terminal Arrangement of the XW2D-20G6 Connector-Terminal Block Conversion Unit





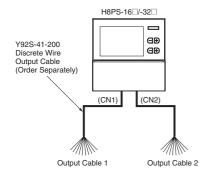
Cam

Cam

Output Cable 2 Wiring Table

Outputs	Connector pin No.	Outputs	Connector pin No.
Cam 17	20	Cam 25	19
Cam 18	18	Cam 26	17
Cam 19	16	Cam 27	15
Cam 20	14	Cam 28	13
Cam 21	12	Cam 29	11
Cam 22	10	Cam 30	9
Cam 23	8	Cam 31	7
Cam 24	6	Cam 32	5
СОМ	4	СОМ	3
Vs	2	Vs	1

2. Y92S-41-200 Discrete Wire Output Cable (Order Separately) Connections



Output Cable 1 Wiring Table

Outputs	Cable color	Marks	Marking color	Outputs	Cable color	Marks	Marking color
Cam 1	Orange		Black	Cam 9	Orange		Red
Cam 2	Gray		Black	Cam 10	Gray		Red
Cam 3	White		Black	Cam 11	White		Red
Cam 4	Yellow		Black	Cam 12	Yellow		Red
Cam 5	Pink		Black	Cam 13	Pink		Red
Cam 6	Orange		Black	Cam 14	Orange		Red
Cam 7	Gray		Black	Cam 15	Gray		Red
Cam 8	White		Black	Cam 16	White		Red
СОМ	Yellow		Black	СОМ	Yellow		Red
Vs	Pink		Black	Vs	Pink		Red

Output Cable 2 Wiring Table

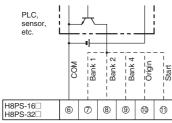
Outputs	Cable color	Marks	Marking color	Outputs	Cable color	Marks	Marking color
Cam 17	Orange		Black	Cam 25	Orange		Red
Cam 18	Gray		Black	Cam 26	Gray		Red
Cam 19	White		Black	Cam 27	White		Red
Cam 20	Yellow		Black	Cam 28	Yellow		Red
Cam 21	Pink		Black	Cam 29	Pink		Red
Cam 22	Orange		Black	Cam 30	Orange		Red
Cam 23	Gray		Black	Cam 31	Gray		Red
Cam 24	White		Black	Cam 32	White		Red
СОМ	Yellow		Black	СОМ	Yellow		Red
Vs	Pink		Black	Vs	Pink		Red

■ Input Connections

Only the Encoder inputs are connected with 8-output Models. The inputs are no-voltage (short-circuit or open) inputs.

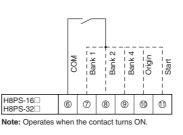
No-voltage Inputs

Open Collector



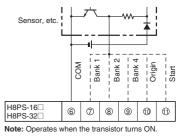
Note: Operates when the transistor turns ON.

Contact Input



Voltage-output sensors can also be connected.

Connection Examples



No-voltage Input Signal Levels

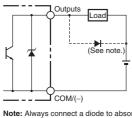
No-contact inputs	Short-circuit level for transistor ON
	 Residual voltage: 2 V max.
	 Impedance when ON: 1 kΩ max. (The leakage current is approx. 2 mA when the impedance is 0 Ω)
	Open level for transistor OFF
	• Impedance when OFF: 100 k Ω min.
Contact inputs	Use a contact that can adequately switch 2 mA at 5 V.

Note: Use a maximum DC power supply of 30 V.

Output Connections

Note: Internal circuit damage may result from a short circuit in the load.

NPN Output Models

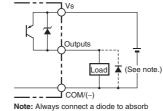


Note: Always connect a diode to absorb counter-electromotive force when connecting an inductive load.

Item	Cam outputs, Pulse outputs, RUN output	
Output method	NPN open collector	
Dielectric strength	30 VDC	
Rated current	100 mA (See note.)	30 mA
Residual voltage	2 VDC max.	0.5 VDC max.
Leakage current	100 μA max.	5 μA max.

Note: Do not exceed 1.6 A total for all cam outputs and the RUN output.

PNP Output Models



counter-electromotive force when connecting an inductive load.

Item	Cam outputs, Pulse outp RUN output	
Output method	PNP open collector	
Dielectric strength	8-output Models: 30 VDC 16-/32-output Models: 26.4 VDC	
Rated current	100 mA (See note.) 30 mA	
Residual voltage	2 VDC max.	
Leakage current	100 μA max.	

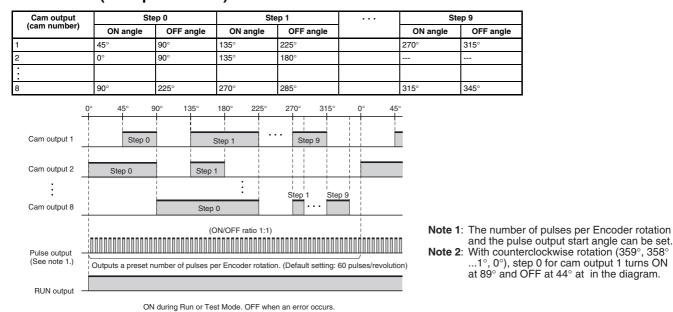
Note: Do not exceed 1.6 A total for all cam outputs and the RUN output.

Operating Mode

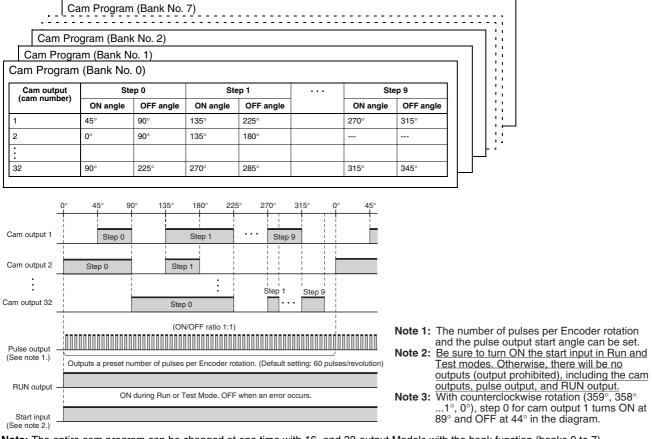
Functions

The H8PS Cam Positioner receives angle signal inputs from the Dedicated Absolute Encoder and outputs the preset ON/OFF angles as cam outputs. **Program Examples**

1. H8PS-8 (8-output Models)

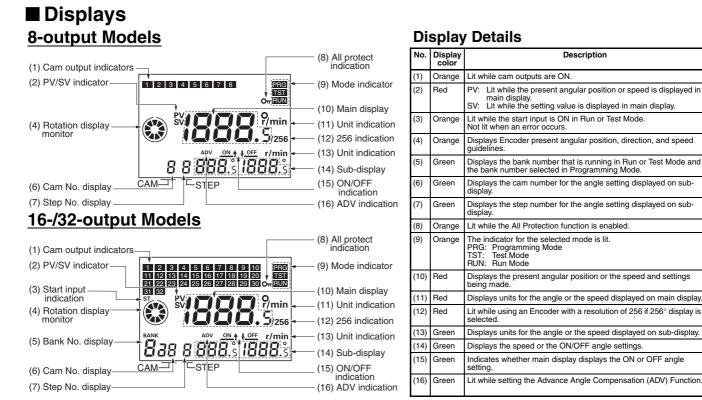


2. H8PS-16 /-32 (16-/32-output Models)

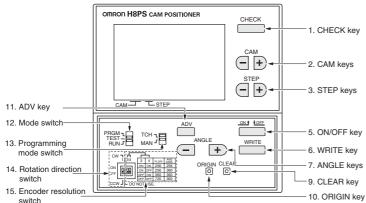


Note: The entire cam program can be changed at one time with 16- and 32-output Models with the bank function (banks 0 to 7). For details on the procedure for switching banks, refer to page 126.

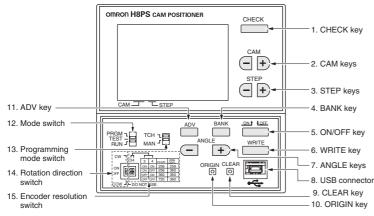
Nomenclature



Operation Keys 8-output Models



16-/32-output Models



Operation Key Details

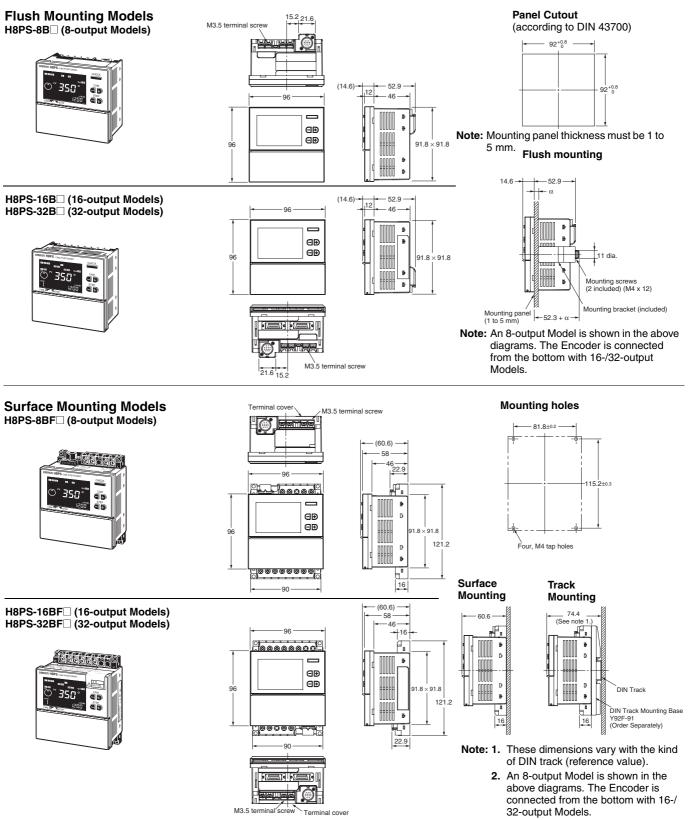
No.	Description		
1	Displays program details in Run Mode.		
2	Selects the cam number with 🛨 🗕 Keys.		
3	Selects the step number with 🛨 🖃 Keys.		
4	Selects the bank number.		
5	Selects the ON angle, or OFF angle		
6	Writes the set data to memory.		
7	Changes the angle or other setting value with + - Keys.		
8	Connects the Cam Positioner to a personal computer via USB cable (orde separately) for programming with the Support Software (order separately)		
9	Moves to the screen for clearing settings		
10	Designates the current angle of the machine (Encoder) as the origin (0°)		
11	Programming or Test Mode: Press to shift to the ADV function setting screen. Programming Mode: Press and hold at least 3 s to shift to the Function Setting Mode. Run Mode: Press and hold at least 5 s to enable/disable the All Protection function.		
12	Switches modes. Programming Mode (PRGM): Used to write cam programs, set the ADV function, etc. Test Mode (TEST): Used to modify settings while the Encoder is running Run Mode (RUN): Used for normal operation and to check the cam program.		
13	Select the method used for programming cams. Teaching: ON/OFF Angles can be set based on actual machine (Encoder operation. Manual: ANGLE Keys can be used to set ON/OFF angles.		
14	Sets the H8PS rotation direction (rotation display monitor, etc.) to the machine (Encoder) rotation direction.		
15	Sets the resolution of the connected Encoder. Also sets the unit for angle display when using an Encoder with a resolution of 256.		

Dimensions

Note: All units are in millimeters unless otherwise indicated.

Main Unit

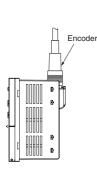
Cam Positioners

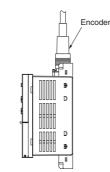


Encoder Connecting Direction

H8PS-8B

H8PS-8BF





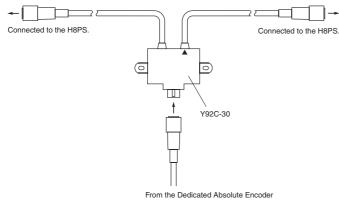
■ Accessories (Order Separately)

Parallel Input Adapters

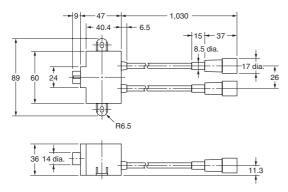
Y92C-30

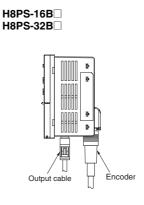
This Adapter enables two H8PS Cam Positioners to share signals from an Encoder.

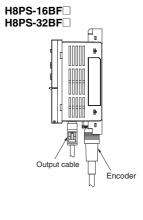




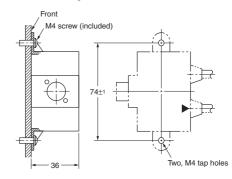
Use the cable marked with a triangle when connecting only one H8PS Cam Positioner to the Parallel Input Adapter.



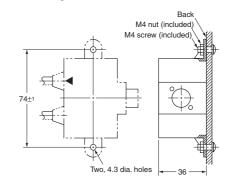




Panel Surface Mounting



Panel Back Mounting

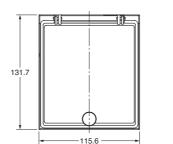


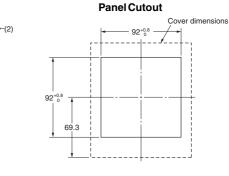
Accessories (Order Separately)

Watertight Cover

Y92A-96N







Use for flush mounting when waterproofing is required. The Y96A-96N conforms to IP66 and

NEMA4 (for indoor use) standards for waterproofing. The operating environment may cause the waterproof packing to deteriorate, shrink, or harden.

Therefore, it is recommended that the packing be replaced regularly.

keys or switches.

Protective Cover

Y92A-96B



A hardened Y92A-96B Protective Cover is available. Use it for the following: To protect the front panel from dust and dirt.

• To prevents the set value from being altered due to accidental contact with the



DIN Track Mounting Base

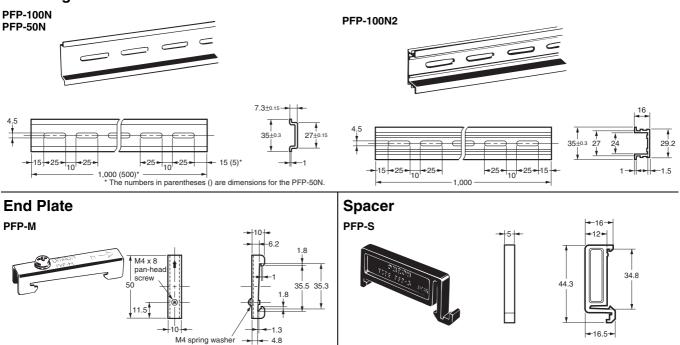
21.9

Ø





Mounting Track



E6CP-A/E6C3-A/E6F-A Rotary Encoders (Absolute)

- Combining this Encoder with an H8PS Cam Positioner enables high-precision detection of the operation timing of various automatic machines.
- The E6CP-A is a low-cost, money-saving Encoder.
- The standard E6C3-A is well suited to environments subject to water and oil.
- The standard E6F-A is a rigid type that is compatible with high shaft-tolerance applications as well as environments subject to water and oil.

Note: Refer to the relevant datasheet for details.

Ratings and Characteristics

Item	1	E6CP-AG5C-C E6C3-AG5C-C		E6F-AG5C-C		
Rated supply	voltage	12 VDC -10% to 24 VDC +15%, ripple (p-p) 5				
Current cons (See note 1.)		n 70 mA max.		60 mA max.		
Resolution (p per rotation)	oulses	256 (8-bit)	256 (8-bit), 360 (9-bit), or 720 (10-bit)			
Output code		Gray binary				
Output config	guration	NPN open-collector output				
Output capad	city	Applied voltage: 28 VDC max. Sink current: 16 mA max. Residual voltage:0.4 V max. (sink current at 16 mA)	Applied voltage: 30 VDC max. Sink current: 35 mA max. Residual voltage:0.4 V max. (sink current at 35 mA)			
Logic		Negative logic ($H = 0, L = 1$)				
Accuracy		Within ±1°				
Rotation dire	ction	Clockwise (viewed from the shaft) for output co	ode increment			
Rise and fall output	times of	of 1.0 μs max. (control output voltage: 16 V; load 1.0 μs max. (control output voltage: 5 V; load resistance: 1 kΩ; output cord: 2 m max.)				
Starting torq			9.8 m N·m max. (at room temperature), 14.7 m N·m max. (at low temperature)			
Moment of in	ertia	$1 \times 10^{-6} \text{ kg} \cdot \text{m}^2 \text{ max.}$ $2.3 \times 10^{-6} \text{ kg} \cdot \text{m}^2 \text{ max.}$		$1.5 \times 10^{-6} \text{ kg} \cdot \text{m}^2 \text{ max.}$		
Shaft-load	Radial	30 N	80 N	120 N		
tolerance Thrust		20 N	50 N			
Max. permise rotation	sible	1000 r/min	5000 r/min			
Ambient tem	perature	−10 to 55°C (with no icing)	–10 to 70°C (with no icing)			
Storage temp	perature	–25 to 85°C (with no icing)		–25 to 80°C (with no icing)		
Ambient hum	nidity	35% to 85% (with no condensation)				
Degree of protection IEC standard IP50		IEC standard IP50	IEC standard IP65 (JEM standard IP65f) (See note 2.)	IEC standard IP65 (JEM standard IP65f)		
Insulation resistance 20 MΩ min. (at 500 VDC) between charged parts and the case		arts and the case				
Dielectric str	ength	500 VAC, 50/60 Hz for 1 min between charged parts and the case				
Vibration resistance		Destruction: 10 to 55 Hz,1.5-mm double amplitude for 2 hr each in X, Y, and Z directions	Destruction: 10 to 500 Hz, 2-mm double amplitude, 150 m/ $\rm s^2$ 3 times each in X, Y, and Z directions, 11- min sweep time	Destruction: 10 to 500 Hz,1.5-mm double amplitude 3 times each in X, Y, and Z directions, 11-min sweep time		
Shock resista	ance	Destruction: 1000 m/s ² 3 times each in X, Y, and	nd Z directions			
Weight		Approx. 200 g (with 2-m cord)	Approx. 300 g (with 1-m cord)	Approx. 500 g (with 2-m cord)		
Datasheet Ca	Datasheet Cat. No F058		F058	E283		

Note: 1. The following inrush currents flow when the power is turned ON. E6CP-AG5C-C: Approx. 8 A (time: approx. 0.3 ms), E6C3-AG5C-C: Approx. 6 A (time: approx. 0.8 ms), E6F-AG5C-C: Approx. 9 A (time: approx. 5 µs)

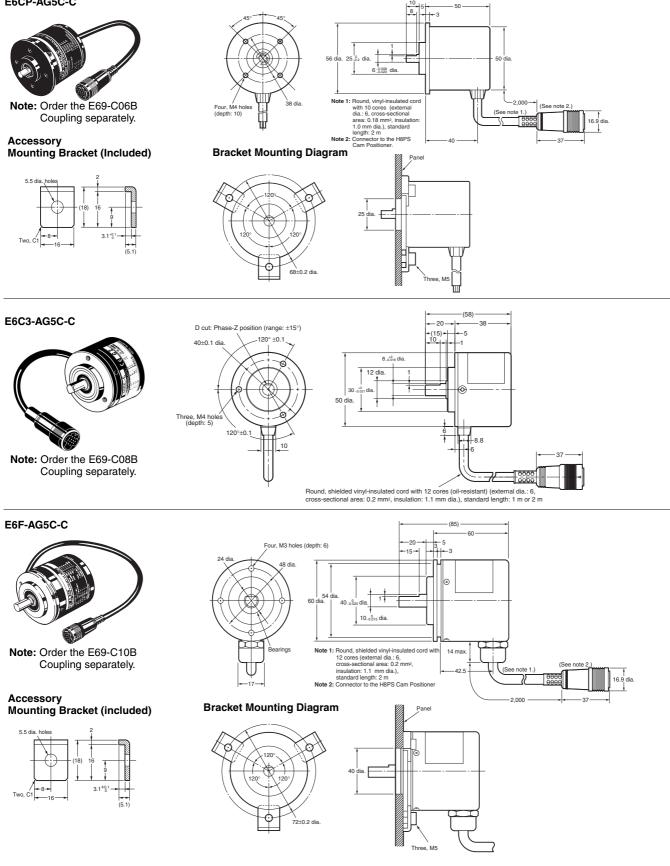
2. JEM1030: Applicable as of 1991



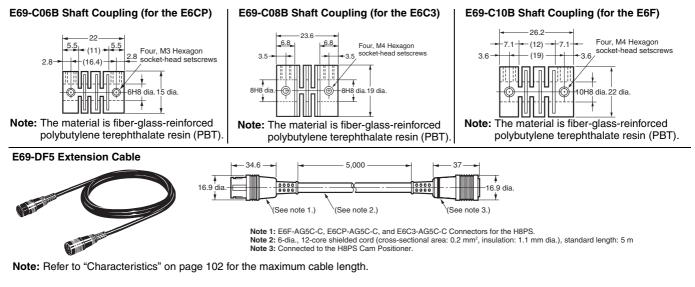
Dimensions

Note: All units are in millimeters unless otherwise indicated.

E6CP-AG5C-C



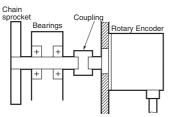
Accessories (Order Separately)



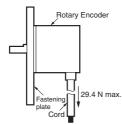
Safety Precautions (Encoder)

Precautions for Correct Use

- Do not subject the E6CP Encoder to oil or water.
- The Encoder consists of high-precision components. Handle it with utmost care and do not drop it, otherwise malfunctioning may result.
- When connecting the shaft of the Encoder with a chain timing belt or gear, connect the chain timing belt or gear with the shaft via a bearing or coupling as shown in the following diagram.

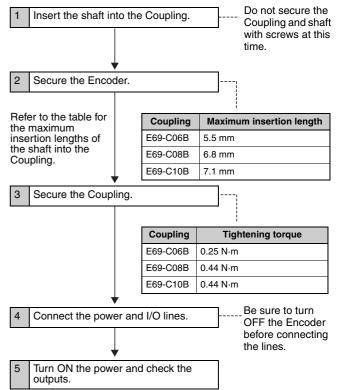


- If the decentering or declination value exceeds the tolerance, an excessive load imposed on the shaft may damage or shorten the life of the Encoder.
- Do not place excessive loads on the shaft if the shaft is connected to a gear.
- The tightening torque must not exceed the value given in the table at the right when the Rotary Encoder is mounted with screws.
- Do not pull wires with a force greater than 29.4 N while the Rotary Encoder is secured and wired.



- Do not subject the shaft to shock. Therefore, do not strike the shaft or coupling with a hammer when inserting the shaft into the coupling.
- Make sure there is no foreign matter in the Connector before connecting it to the Encoder.

Mounting Procedure



Safety Precautions (Cam Positioner)

Tighten terminal screws to a torque of 0.80 N·m so that they do not become loose. Minor fires or malfunction may occasionally occur.

For 16- and 32-output Models, leave the protective label attached to the H8PS when wiring. Removing the label before wiring may occasionally result in fire if foreign matter enters the Unit.



Remove the label after the completion of wiring to ensure proper heat dissipation. Leaving the label attached may occasionally result in fire.

Do not disassemble, modify, or repair the H8PS or touch any of the internal parts. Otherwise, minor electric shock, fire, or malfunction may occasionally occur.

Do no allow metal fragments, lead wire scraps, or chips from processing during installation to fall inside the H8PS. Otherwise, minor electric shock, fire, or malfunction may occasionally occur.

Do not touch the terminals when power is being supplied. For Surface-mounting H8PS, always connect the terminal cover for after completing wiring. Otherwise, minor injury due to electric shock may occasionally occur.



Observe the following items to ensure the safe use of this product.

Environmental Precautions

- Store the H8PS within specified ratings. If the H8PS has been stored at temperatures -10°C or lower, let it stand for 3 hours or longer at room temperature before turning ON the power supply.
- Use the H8PS within the specified ratings for operating temperature and humidity.
- Do not operate the H8PS in locations subject to sudden or extreme changes in temperature, or locations where high humidity may result in condensation.
- Do not use the H8PS in locations subject to vibrations or shock. Extended use in such locations may result in damage due to stress.
- Do not use the H8PS in locations subject to excessive dust, corrosive gas, or direct sunlight.
- Install the H8PS well away from any sources of static electricity, such as pipes transporting molding materials, powders, or liquids.
- The H8PS is not waterproof or oil resistant. Do not use it in locations subject to water or oil.
- · The life expectancy of internal components may be reduced if the H8PS is mounted side-by-side.
- Do not use organic solvents (such as paint thinner or benzine), strong alkaline, or strong acids because they will damage the external finish.

Usage Precautions

- · Install a switch or circuit breaker that allows the operator to immediately turn OFF the power, and label it to clearly indicate its function
- · Pay careful attention to polarity to avoid wrong connections when wiring terminals.
- · Do not connect more than two crimp terminals to the same terminal.
- Use the specified wires for wiring. Applicable Wires

AWG24 to AWG18 (cross-sectional area of 0.208 to 0.832 mm²) Solid or twisted wires of copper

- · Do not connect loads that exceed the rated output current. The output elements may be destroyed, possibly resulting in shortcircuit or open-circuit faults.
- · Always connect a diode to protect against counterelectromotive force when using an inductive load. Counterelectromotive force may destroy output elements, possibly resulting in short-circuit or open-circuit faults.
- Use the specified cables to connect outputs.
- Do not install input lines in the same duct or conduit as power supply or other high-voltage lines. Doing so may result in malfunction due to noise. Separate the input lines from highvoltage lines.
- · Internal elements may be destroyed if a voltage outside the rated voltage is applied.
- · Maintain voltage fluctuations in the power supply within the specified range.
- · Use a switch, relay, or other contact so that the rated power supply voltage will be reached within 0.1 s. If the power supply voltage is not reached quickly enough, the H8PS may malfunction or outputs may be unstable.
- Do not turn OFF the power supply when changing or deleting settings. The contents of the EEPROM may be corrupted.







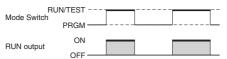
Precautions for Correct Use

 A cam output will remain ON if the set angles for two steps overlap for the same cam number.

Step 1: 120° ON \rightarrow 170° OFF Step 2: 150° ON \rightarrow 210° OFF

ON				
OFF —			XXX////	
OFF —	120°	150°	170°	210

- A step will produce no output if the ON and OFF angle for the step are the same.
- The RUN output does not turn ON during programming.



- Note: The RUN output turns ON with the timing shown in the diagram, but it remains OFF when an error occurs. Thus, you can use the output as a timing signal during operation, including trial operation.
- Input signals may be accepted, not accepted, or unstable for the following times when the power supply is turned ON or OFF. Set the system to allow leeway in the timing of input signals. Approx. 1 second is required from the time the power supply is turned ON until outputs are made. Refer to the *Operation Manual* (Cat. No. Z199) for information on other timing.



• When using 16-/32-output Modules, the operation timing of the outputs will be as shown below in relation to the ON/OFF timing of the start input. Refer to *Bank Functions (F7/F8/F9)* on page 127 when switching banks.

ON Start input OFF					
OFF		225 ms	max.	225 ms	max.
Cam outputs RUN output	Outpu	t OFF	Output p	ossible	Output OF

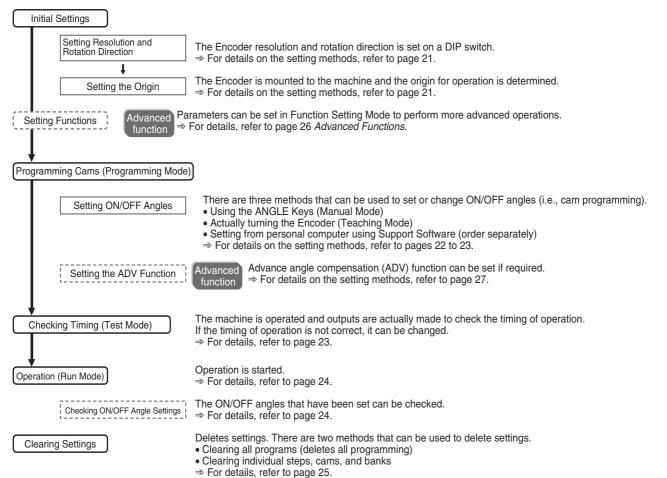
- Do not subject H8PS Connectors (outputs, Encoder) to more than 30 N of force.
- Confirm the waveform of the power supply circuit and install a surge absorber. Surge or noise applied to the power supply may destroy internal elements or cause malfunctions.
- Switch the power supply circuit with a device rated at 3.5 A or higher.
- Inrush current of approximately 3.5 A will flow for a short period of time when the power supply is turned ON. The H8PS may not start if the capacity of the power supply is not sufficient. Be sure to use a power supply with sufficient capacity.
- EEPROM is used as memory when the power is interrupted. The write life of the EEPROM is 100000 writes. The EEPROM is written when settings are changed or deleted or when the resolution is changed.
- Make sure that all settings are appropriate for the application. Unexpected operation resulting in property damage or accidents may occur if the settings are not appropriate.
- Connect all negative (-) terminals, COM terminals, and Vs terminals.
- When using the Y92C-30 Parallel Input Adapter for parallel operation, do not connect more than two H8PS Cam Positioners to the same Encoder.

0

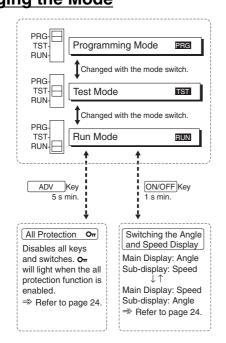
Refer to the following manual for precautions in using the Cam Positioner and other information required for operation: H8PS Cam Positioner Operation Manual (Cat. No. Z199)

Operating Procedures

■ Flow of Operation



■ Settings for Basic Functions Changing the Mode



Programming Mode

Used to write cam programs, set the advance angle compensation function, etc. All outputs will remain OFF.

Test Mode

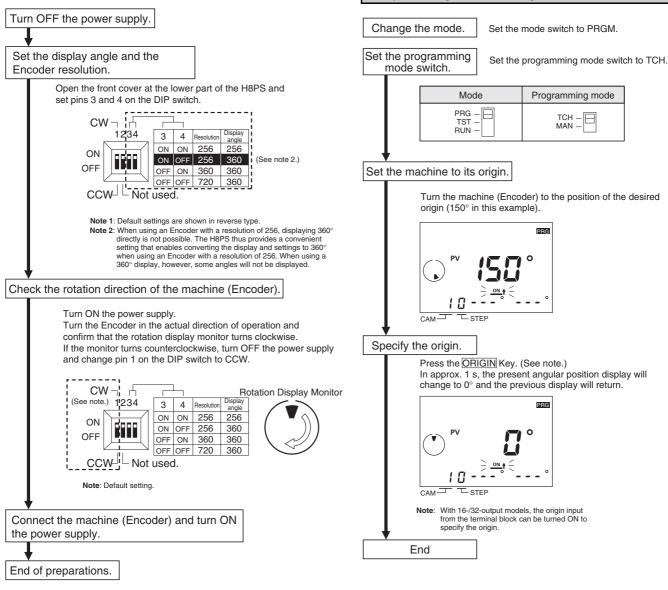
Used to write cam programs, set the advance angle compensation function, and perform other operations while actually turning ON outputs to confirm operation timing. This mode is also used to adjust settings during operation.

Run Mode

Used for normal operation. Settings, such as writing cam programs and setting the advance angle compensation function, cannot be performed.

Setting Resolution and Rotation Direction

One of three resolutions can be selected for the Encoder connected to the H8PS: 256, 360, or 720. The resolution and display angle are set here.



Setting the Origin

The origin of the Cam Positioner is set to match the origin of the machine (Encoder). The same origin is used for all banks.

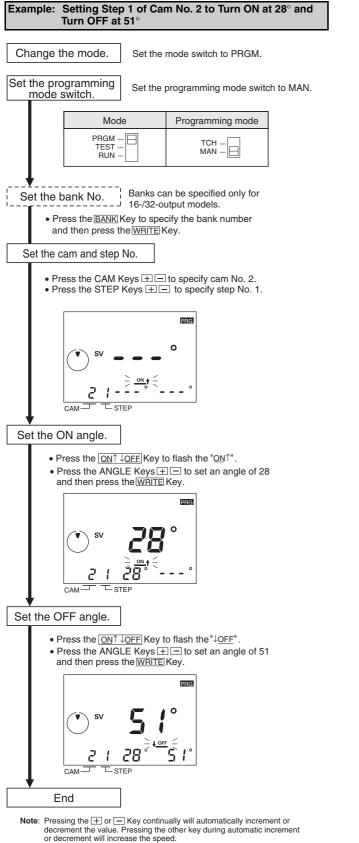
(The bank function is supported only for 16-/32-output models.)

Example: Setting the Present Angular Position of 150° to 0°

Note: Changes to DIP switch settings are enabled when the power is turned ON.

Setting ON/OFF Angles in Manual Mode

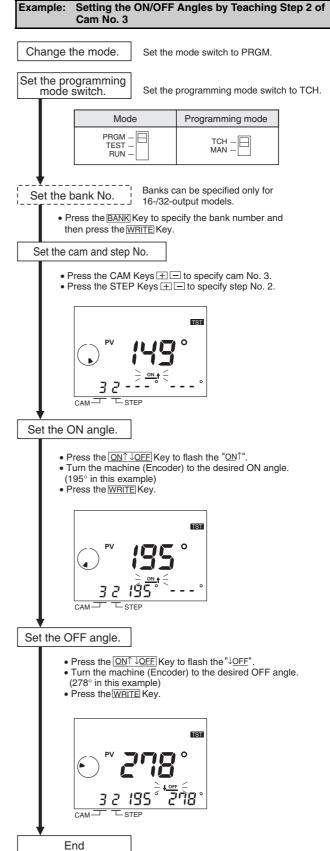
ON/OFF angles can be set manually using the ANGLE Keys \pm = on the front of the Cam Positioner.



Setting ON/OFF Angles in Teaching

Mode

ON/OFF angles can be set based on actual machine (Encoder) operation.



Setting ON/OFF Angles Using Support Software

With 16-/32-output models, programs can be uploaded or downloaded easily with the optional Support Software (H8PS-SOFT-V1) by connecting a personal computer to the Cam Positioner using the optional Y92S-40 USB cable.

Support Software Functions

- Writing cam programs
- Setting functions
- Editing, saving, and printing programs
- Displaying and printing cam program operation charts
- Simple simulations of programs Applicable OS: Windows 98, 2000, ME, or XP

Refer to the user's manual for the Support Software for details.

Checking Timing (Test Mode)

Testing Operation

Operation can be tested to check operation timing.

• Set the mode switch to TEST.



• Operate the Encoder and check the timing of operation.



• If the timing is not correct, change the ON/OFF angle settings. The settings can be changed in Test Mode.

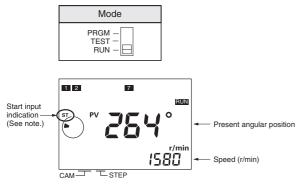
- **Note: 1.** Outputs will turn ON and OFF in Test Mode. Confirm system safety before switching to Test Mode.
 - 2. With 16-/32-output model, be sure to turn ON the start input. Outputs are not turned ON unless the start input is turned ON.



Operation (Run Mode)

Starting Operation

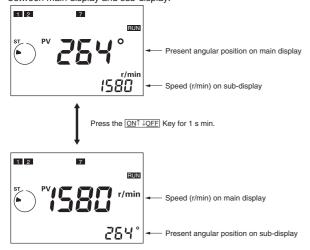
• Set the mode switch to RUN to start operation.



Note: For 16/32-output models, be sure that the start input is ON and that the start input indicator is lit. Outputs (including the cam, pulse, and run outputs) will not function if the start input is OFF. The 8-output models do not have a start input.

Switching the Angle and Speed Displays

• Press the ONT JOFE Key for at least 1 s in Run Mode to reverse the display positions of the present angular position and speed (r/min) between main display and sub-display.



All Protection Function

The all protection function locks the H8PS in Run Mode and prohibits any changes to settings. It can be used to prevent incorrect or unauthorized operation. If the $\boxed{\text{ADV}}$ Key is pressed for at least 5 s in Run Mode, the All Protection indicator \bigcirc_{π} will light on the display and all keys and switches will be disabled. If the mode switch is changed to Programming or Test Mode while protection is enabled, the All Protection indicator \bigcirc_{π} will flash to indicate that settings cannot be changed. If a setting on the DIP switch is changed while protection is enabled, the All Protection indicator \bigcirc_{π} will flash when the power supply is turned ON to indicate that settings cannot be changed.





All Protection Function Enabled



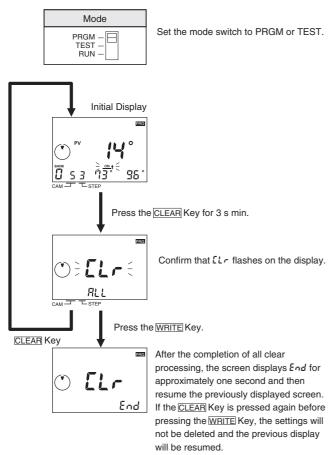
Checking ON/OFF Angle Settings

• During Run Mode, the CAM Keys \square and STEP Keys \square can be used to check the ON/OFF angle settings for any step. Also, the <u>CHECK</u> Key can be pressed to check the ON/OFF angle settings in order for all steps starting from cam 1. If there is no key operation for 10 s or longer during the checking operation, the previous display will be resumed.

Clearing Settings

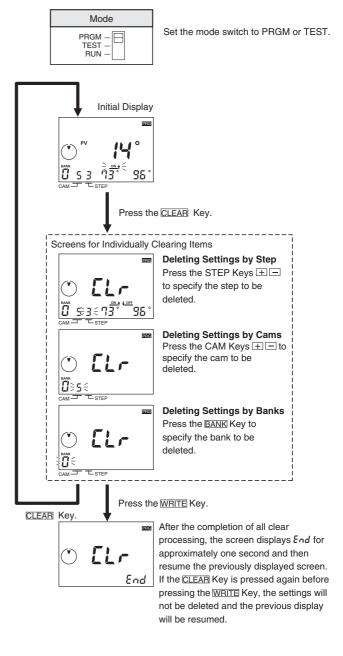
Clearing All Programs

The all clear function can be used to delete all cam programs, the settings for advance angle compensation function, and all other settings. All settings in the Function Setting Mode will be returned to their default settings.



Clearing Individual Steps, Cams, and Banks

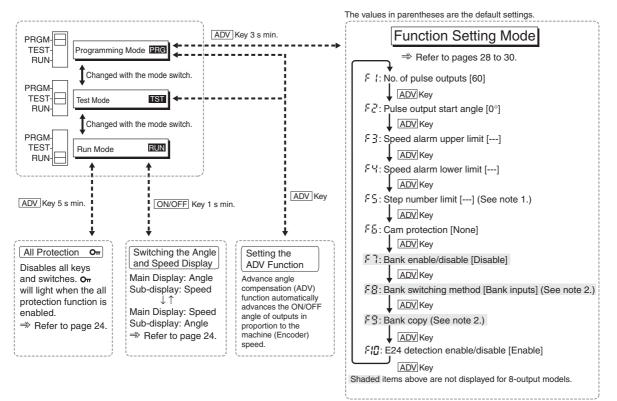
ON/OFF angle settings can be deleted by step, by cam, or by bank. If settings are deleted by cam, the settings for the advance angle compensation (ADV) function will not be deleted. If settings are deleted by bank, the settings for the ADV function will also be deleted. Settings in the Function Setting Mode will not be deleted.



Advanced Functions

Set the advanced functions as required to perform more advanced operation. Outlines of the advanced functions are provided on the following pages. For details, refer to the *Operation Manual* (Cat. No. Z199).

Mode Transitions

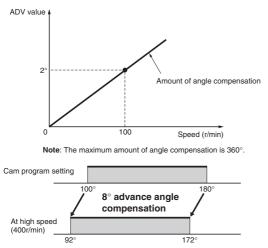


Note 1: The default setting is for 10 steps for all cams. Note 2: Not displayed when F7 is disabled.

Advance Angle Compensation (ADV) Function

The advance angle compensation function automatically advances the ON/OFF angle of cam outputs in proportion to machine (encoder) speed. As the speed of the machine increases, the system can be affected by the delay in outputs. If the ADV function is used, the output delay caused by higher speeds is automatically compensated.

As shown in the following diagram, ADV function is used to linearly compensate outputs according to the speed based on the ADV value setting for a specific speed.



Example: ADV Value Set to 2° at 100 r/min

ADV value can be set independently for cams 1 to 7 (7 total). For the ADV function, the speed and the amount of angle compensation are set. If "- - -" is displayed for any setting, the ADV function is disabled. The setting ranges are given in the following table.

Encoder		Speed	ADV value
Resolution	Display angle		
256	256	"", 1 to 1,600	" ", 0 to 255
256	360	"", 1 to 1,600	" ", 0 to 359
360		"", 1 to 1,600	" ", 0 to 359
720		"", 1 to 800	"", 0 to 359.5

Note: Default settings are shown in reverse type.

The maximum response speed will decrease as shown in the following table when ADV values are set for 4 cams or more.

Number of cams with ADV settings	Encoder resolution	Max. response speed
0 to 3	256/360	1,600r/min
	720	800r/min
4 to 7	256/360	1,200r/min
	720	600r/min

Note: Even if the ADV value is set to 0°, the cam must be included in the number of cams with ADV settings.

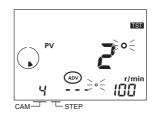
Example: Setting the ADV Value to 2° at 100 r/min for Cam 4

- 1. Set the mode switch to PRGM or TEST.
- 2. Set cam number 4 with the CAM Keys <u>+</u>. (See note.)
- Press the <u>ADV</u> Key to move to the ADV function setting display and confirm that "ADV" is displayed.

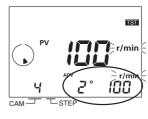
Setting Display



 Set the speed to 100 with the ANGLE Keys <u>+</u> − and then press the <u>WRITE</u> Key.



5. Set the ADV value to 2 with the ANGLE Keys \pm .

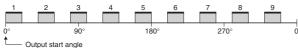


- 6. Press the WRITE Key to write the settings to memory.
- 7. Press the <u>ADV</u> Key after finishing setting the ADV function. The previous display in Programming or Test Mode will be resumed.
- **Note:** If the bank function is being used, set the bank number before setting the cam number.

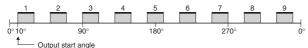
Pulse Output (F ://F2)

Outputs a preset number of pulses per Encoder rotation. Pulses are output at a 1:1 ON/OFF ratio and pulse output can be started from a specified angle.

Operation for 9 Output Pulses and a Start Angle of 0°



Operation for 9 Output Pulses and a Start Angle of 10°



Number of Output Pulses (F 1)

Select the number of pulses per rotation from the following table.

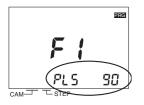
Encoder resolution	Settable number of pulses		
256	1, 2, 3, 4, 5, 6, 9, 10, 12, 15, 18, 20, 30, 36, 45, <mark>60</mark> , 90		
360	1, 2, 3, 4, 5, 6, 9, 10, 12, 15, 18, 20, 30, 36, 45, <mark>60</mark> , 90, 180		
720	1, 2, 3, 4, 5, 6, 8, 9, 10, 12, 15, 18, 20, 24, 30, 36, 40, 45, 60, 72, 90, 120, 180, 360		

Note: Default settings are shown in reverse type.

Example: Setting 90 Pulses per Rotation

The number of pulses is set using the F1 menu in the Function Setting Mode.

Setting Display



Set the number of pulses with the ANGLE Keys \pm and then press the WRITE Key.

Pulse Output Start Angle (F2)

The setting ranges are given in the following table.

Enco	oder	Start angle
Resolution	Display angle	
256	256	0 to 255°
256	360	Oto 359° (See note 2.)
360		0 to 359°
720		0 to 359.5°

Note: 1. Default settings are shown in reverse type.

 The output accuracy is 2° maximum, so not all angles can be set.

Example: Setting the Pulse Output Start Angle to 100 $^\circ$

The starting angle for pulse outputs is set using the F2 menu in the Function Setting Mode.

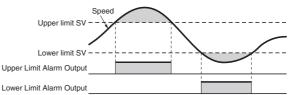
Setting Display



Set the pulse output start angle to 100 with the ANGLE Keys $_{\fbox \boxdot}$ and then press the $_{\fbox WBITE}$ Key.

Speed Alarm Outputs (F 3/F 4)

Specific cam outputs can be used as Encoder speed alarm outputs. Alarms can be output for upper and lower speed limits.



The speed alarm outputs are assigned to cam outputs as shown in the following table. The speed alarms are set to "- - -" for the default settings, i.e., the normal cam outputs are enabled. If a speed alarm is set to any value but "- - -", the normal cam output for the corresponding cam number will be disabled.

	Upper Limit Alarm Output	Lower Limit Alarm Output
H8PS-8□ (8 outputs)	Cam 7	Cam 8
H8PS-16 (16 outputs)	Cam 15	Cam 16
H8PS-32 (32 outputs)	Cam 31	Cam 32

The setting ranges for the upper and lower limits speed alarm are given in the following table.

Encoder resolution	Speed
256, 360	"" or 0 to 1,600 r/min
720	"" or 0 to 800 r/min

Note: Default settings are shown in reverse type.

Speed Alarm Upper Limit (F3)

Example: Setting the Upper Limit Set Value to 700 r/min for a 16output Model

The upper limit set value is set using the F3 menu in the Function Setting Mode.

Upper Limit Setting Display



Set the upper limit set value to 700 with the ANGLE Keys \pm and then press the WRITE Key. (See note.)

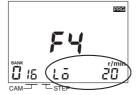
Note: If banks are being used, the bank number must be set.

Speed Alarm Lower Limit (FY)

Example: Setting the Lower Limit Set Value to 20 r/min for a 16-
output Model

The lower limit set value is set using the F4 menu in the Function Setting Mode.

Lower Limit Setting Display



Set the upper limit set value to 20 with the ANGLE Keys \pm and then press the WRITE Key.

Note: If banks are being used, the bank number must be set.

Step Number Limit (F5)

With the H8PS, up to 10 steps can be set to turn the output ON/OFF 10 times for each cam. The number of steps that can be set, however, can be restricted to prevent programming from being added through operating mistakes. Settings can be made for all cams at once or each cam individually. The default setting for the Step Number Limit is 10 steps for all cams.

Example: Limiting the Number of Steps to 2 for All Cams Collectively.

The maximum number of steps to be set is set using the F5 menu in the Function Setting Mode.

Display for Collective Settings



Set the cam number to \mathcal{R} with the CAM Keys \pm and set the maximum number of steps to 2 with the Angle Keys \pm \equiv . Press the WRITE Key to write the setting to memory.

The cam number can be set to R on the setting display to set all cams at once. If the number of steps is displayed as "---" when the cam number is R, the collective settings for all cams are disabled.

Example: Limiting the Number of Steps to 1 for Cam 3.

The maximum number of steps to be set is set using the F5 menu in the Function Setting Mode.

Display for Individual Settings



Set the cam number to 3 with the CAM Keys \pm and set the maximum number of steps to 1 with the Angle Keys \pm . Press the WRITE Key to write the setting to memory.

Cam Protection (Fb)

Cam programs can be write-protected. Use this setting to protect the programs for only specific cam numbers. Protected cam numbers will not be displayed in Programming Mode or Test Mode. Writing or changing programs will not be possible. Protected cam numbers will also not be displayed in Run Mode and cannot be checked. The default settings are for no protection for all cams.

Example: Protecting Cam 3 with an 8-output Model

Cam protection is set using the F6 menu in the Function Setting Mode.

Setting Display



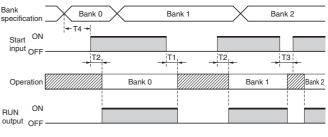
Set the cam number to be protected (and not displayed) to 3 with the CAM Keys \pm and then press the <u>WRITE</u> Key. The output display will go out.

Bank Functions (F7/F8/F9)

The bank function is supported by 16-/32-output models. Banks enable changing the entire cam program at once by switching bank numbers (0 to 7).

Cam Program (Bank No. 7)												
Cam Pi	Cam Program (Bank No. 2)											
Cam Progr	am (Bar	k No. 1)										
Cam Program	Cam Program (Bank No. 0)											
Control output	Step	0	Step	1		Step	9					
(cam number)	ON angle	OFF angle	ON angle	OFF angle		ON angle	OFF angle		μ			
1	1 45° 90° 135° 225° 270° 315°											
2	2 0° 90° 135° 180°											
32	90°	225°	270°	285°		315°	345°					

In Run Mode or Test Mode, the start input must be turned OFF and ON as shown in the following diagram in order to change banks. Control the start input when changing banks.



Unstable region (outputs OFF)

Bank Enable/Disable (F7)

The default setting disables the bank function. To use banks, change the setting using the F7 menu in the Function Setting Mode.

Setting Display



Enable or disable the bank function with the ANGLE Keys \pm = .



T1: 225 ms max. T2: 400 ms max. T3: 20 ms min. T4: 20 ms min.



Bank Switching Method (FB)

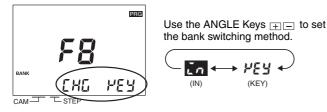
The following methods can be used to switch the bank: the bank inputs on the terminal block or the BANK Key on the front of the Cam Positioner. The method is set using the F8 menu in the Function Setting Mode.

Setting	Display	Description							
Bank input (IN)	in	Banks can be changed only with the bank inputs. Even if a different bank number is displayed in Programming Mode, the bank specified with the bank inputs will be used after switching to Run Mode or Test Mode.							
Bank Key (KEY)	YEY	Banks can be changed only with the BANK Key. Bank inputs are disabled.							

Note: 1. Default settings are shown in reverse type.

2. This setting can be made only when the Bank Function (F7) has been enabled.

Setting Display



The bank inputs on the terminal block are used as shown in the following table.

Bank No.	Bank input terminals							
	1	2	4					
0	OFF	OFF	OFF					
1	ON	OFF	OFF					
2	OFF	ON	OFF					
3	ON	ON	OFF					
4	OFF	OFF	ON					
6	ON	OFF	ON					
6	OFF	ON	ON					
7	ON	ON	ON					

ON: Shorted to COM terminal. OFF: Open

Bank Copy (F9)

Programs can be copied between banks. This function is convenient to copy a program to a different bank when only some of the ON/OFF angle settings need to be changed.

Note: This operation can be used only when the Bank Function (F7) has been enabled.

Example: Copying the Program in Bank 2 to Bank 3

Banks are copied using the F9 menu in the Function Setting Mode. Setting Display

1. Set the number of the bank to be copied.



Set bank number 2 (the copy source) with the BANK Key and then press the WRITE Key.

2. Set the number of the bank to receive the copy.



Set bank number 3 (the copy destination) with the $\underline{\mathsf{BANK}}$ Key and then press the $\underline{\mathsf{WRITE}}$ Key.

3. Execute the copy.



Confirm that \mathcal{LPY} is displayed and then press the WRITE Key again.

4. Copying completed.



After completion of copying *End* is displayed for approx. 1 s and the previous display will be resumed.

E24 Detection (F 12)

Displaying E24 errors (Encoder disconnected) can be disabled. The setting does not normally need to be changed. When the Y92C-30 Parallel Input Adapter (order separately) is used to connect more than one H8PS to the same Encoder, an E24 error can appear even if the Encoder connection is normal. If this happens, use the E24 Detection function (F10) in the Function Setting Mode to disable E24 detection displays.

Setting	Display	Description
Enabled	9E5	An E24 error will be displayed if the Encoder is not connected correctly in Run Mode or Test Mode.
Disabled	nõ	An E24 error will not be displayed even if an Encoder is not connected.

Note: Default settings are shown in reverse type.

Setting Display



Enable or disable E24 detection with the ANGLE Keys \pm .



■ Self Diagnostic Function

The following displays will appear on the main display if an error occurs. If an error occurs, all outputs (including cam, pulse, and run outputs) will be turned OFF.

Display	Meaning	Recovery method
200	Origin designation data error	Press the CLEAR Key for at least 3 s. All settings, including the origin designation data, will be initialized.
E	Memory error: RAM error	Cycle the power supply.
E 12	Memory error: Checksum error	Press the CLEAR Key for at least 3 s. All settings, including the origin designation data, will be initialized.
E 13	CPU error	Cycle the power supply.
55 (Response speed exceeded	The Encoder is rotating faster than the allowable range. Reduce the speed to within the allowable range. Then cycle the power supply or switch to Programming Mode and then to Run Mode.
523	Encoder data error	There are surges or noise around the product or in the wiring. Check the wiring and protect the product from surges and noise. Then cycle the power supply.
823	Encoder resolution inconsistent	Set the Encoder resolution according to the specifications of the Encoder. Then cycle the power supply.
624	Encoder disconnected	Connect the Encoder connector properly. Then, cycle the power supply or switch to Programming Mode and then to Run Mode.

OMROD

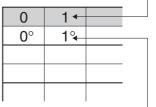
Angle Data Table

To assist with programming when using an Encoder with a resolution of 256/rotation, displays and settings may be done by conversion to 360 degrees by setting a pin on the DIP switch inside the front cover. The following table shows the conversions.

0	,												0			
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
0°	1 °	3 °	4°	6°	7 °	8 °	10°	11°	13°	14°	15°	17°	18°	20°	21°	
16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	
23°	24°	25°	27°	28°	30°	31°	32°	34°	35°	37°	38°	39°	41°	42°	44°	
32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	
45°	46°	48°	49°	51°	52°	53°	55°	56°	58°	59°	60°	62°	63°	65°	66°	
48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	
68°	69°	70°	72°	73°	75°	76°	77°	79°	80°	82°	83°	84°	86°	87°	89°	
64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	
90°	91°	93°	94°	96°	97°	98°	100°	101°	103°	104°	105°	107°	108°	110°	111°	
80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	
113°	114°	115°	117°	118°	120°	121°	122°	124°	125°	127°	128°	129°	131°	132°	134°	
96	97	98	99	100	101	102	103	104	105	106	107	108	109	110	111	
135°	136°	138°	139°	141°	142°	143°	145°	146°	148°	149°	150°	152°	153°	155°	156°	
112	113	114	115	116	117	118	119	120	121	122	123	124	125	126	127	
158°	159°	160°	162°	163°	165°	166°	167°	169°	170°	172°	173°	174°	176°	177°	179°	
128	129	130	131	132	133	134	135	136	137	138	139	140	141	142	143	
180°	181°	183°	184°	186°	187°	188°	190°	191°	193°	194°	195°	197°	198°	200°	201°	
144	145	146	147	148	149	150	151	152	153	154	155	156	157	158	159	
203°	204°	205°	207°	208°	210°	211°	212°	214°	215°	217°	218°	219°	221°	222°	224°	
160	161	162	163	164	165	166	167	168	169	170	171	172	173	174	175	
225°	226°	228°	229°	231°	232°	233°	235°	236°	238°	239°	240°	242°	243°	245°	246°	
176	177	178	179	180	181	182	183	184	185	186	187	188	189	190	191	
248°	249°	250°	252°	253°	255°	256°	257°	259°	260°	262°	263°	264°	266°	267°	269°	
192	193	194	195	196	197	198	199	200	201	202	203	204	205	206	207	256
270°	271°	273°	274°	276°	277°	278°	280°	281°	283°	284°	285°	287°	288°	290°	291°	How to Use t
208	209	210	211	212	213	214	215	216	217	218	219	220	221	222	223	0
293°	294°	295°	297°	298°	300°	301°	302°	304°	305°	307°	308°	309°	311°	312°	314°	0°
224	225	226	227	228	229	230	231	232	233	234	235	236	237	238	239	
315°	316°	318°	319°	321°	322°	323°	325°	326°	328°	329°	330°	332°	333°	335°	336°	
240	241	242	243	244	245	246	247	248	249	250	251	252	253	254	255	
338°	339°	340°	342°	343°	345°	346°	347°	349°	350°	352°	353°	354°	356°	357°	359°	
	I	I	I	I	1	I	I	1	1	I	1	I	I	I	1	360

56 display (Encoder output data)

the Table



360° display (360° converted data)

Warranty and Application Considerations

Warranty and Limitations of Liability

WARRANTY

OMRON's exclusive warranty is that the products are free from defects in materials and workmanship for a period of one year (or other period if specified) from date of sale by OMRON.

OMBON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, REGARDING NON-INFRINGEMENT, MERCHANTABILITY, OR FITNESS FOR PARTICULAR PURPOSE OF THE PRODUCTS. ANY BUYER OR USER ACKNOWLEDGES THAT THE BUYER OR USER ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. OMRON DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED.

LIMITATIONS OF LIABILITY

OMRON SHALL NOT BE RESPONSIBLE FOR SPECIAL, INDIRECT, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS, OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED ON CONTRACT, WARRANTY, NEGLIGENCE, OR STRICT LIABILITY.

In no event shall the responsibility of OMRON for any act exceed the individual price of the product on which liability is asserted. IN NO EVENT SHALL OMRON BE RESPONSIBLE FOR WARRANTY, REPAIR, OR OTHER CLAIMS REGARDING THE PRODUCTS UNLESS OMRON'S ANALYSIS CONFIRMS THAT THE PRODUCTS WERE PROPERLY HANDLED, STORED, INSTALLED, AND MAINTAINED AND NOT SUBJECT TO CONTAMINATION, ABUSE, MISUSE, OR INAPPROPRIATE MODIFICATION OR REPAIR.

Application Considerations

SUITABILITY FOR USE

OMRON shall not be responsible for conformity with any standards, codes, or regulations that apply to the combination of products in the customer's application or use of the products.

Take all necessary steps to determine the suitability of the product for the systems, machines, and equipment with which it will be used.

Know and observe all prohibitions of use applicable to this product.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCTS ARE PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

Disclaimers

CHANGE IN SPECIFICATIONS

Product specifications and accessories may be changed at any time based on improvements and other reasons. Consult with your OMRON representative at any time to confirm actual specifications of purchased product.

DIMENSIONS AND WEIGHTS

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

In the interest of product improvement, specifications are subject to change without notice.