



## **Motion controllers**



Servo-based motion controllers			
Model	JUSP-NS300	JUSP-NS500	JUSP-NS600
	Position controller over DeviceNet	Position controller over PROFIBUS-DP	Position controller over serial link
Axes control method	Direct connection to servo drive	Direct connection to servo drive	Direct connection to servo drive
Connectivity	DeviceNet	PRIFIBUS	RS-485/RS-422
Digital I/O	Uses the servo I/O and adds 2 additional DO and 1 DI	Uses the servo I/O and adds 2 additional DO and 1 DI	Uses the servo I/O and adds 8 additional DI and 6 DO
Application	Point-to-point with registration capability	Poin- to-point with registration capability	Point-to-point with registration capability
Servo control mode	Position, speed	Position, speed	Position, speed
Applicable servo drive	Sigma-II	Sigma-II	Sigma-II
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